

DOMETIC

POWER & CONTROL

INTERACT DRIVE



INTERACT DRIVE

EN **Jackplate and Trim Position Controller**
 User Manual and Troubleshooting Guide

WARNING
 Cancer and Reproductive Harm
www.P65Warnings.ca.gov

Service Center & Dealer Locations

Visit: www.dometic.com

Read these instructions carefully. These instructions **MUST** stay with this product.

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1 Explanation of Symbols and Safety Instructions

Thank you for choosing the Interact Drive. This Installation and Owner’s Manual contains all the information that you and others will require for the safe installation and use of the Interact Drive and **MUST** remain on board the boat. Throughout this manual, information for the safe installation and use of the controller will be distinguished in one of the following ways:

1.1 Recognize Safety Information

⚠ This is the safety alert symbol. It is used to alert you to potential physical injury hazards. Obey all safety messages that follow this symbol to avoid possible injury or death.

1.2 Understand Signal Words

A signal word is used when safety or property damage messages are prompted. Each signal word will also indicate the degree or level of seriousness the hazard presents.

⚠ WARNING

Indicates a hazardous situation that, if **not** avoided, could result in death or serious injury.

Failure to adhere to a warning may lead to loss of steering control. Loss of vessel control may result in unpredictable boat behavior, leading to ejection from boat causing property damage, personal injury and/or death.

⚠ CAUTION

Indicates a hazardous situation that, if **not** avoided, could result in minor or moderate injury.

NOTICE: Indicates important information in regards to installation, use and maintenance of the steering components.

NOTICE: Marine Canada Acquisition Inc. DBA Dometic is referred to as Dometic throughout this publication.

These safety alerts alone cannot eliminate all of the hazards that may be present while on the water. Dometic recommends that all users of the steering system take an accredited 'boating safety course', follow safe boating practices and are made aware of the environment that they will be in.

1.3 Safety Information

The safety information provided below is intended to inform you of the dangers that may be present before, during and after the installation. It is critical that you read and understand ALL the points noted:

- The safe operation of the controller is dependent upon proper installation and maintenance, common sense, safe judgment and the knowledge/expertise of the operator. Every installer/user of the controller should know the following requirements 'before' installing/using the controller.
- If you have any questions regarding any of these warnings, contact Dometic.
- To reduce risk of severe injury or death. Always wear a Coast Guard Approved personal flotation device (PFD) and use an engine shut-off cord (lanyard).
- Read and follow all safety information and instructions.
- Read and understand these instructions before [installing/ operating/ servicing] this product.

1.4 Important Labels

The safety information provided below is intended to inform you of the warning information on your product. Please contact Dometic if the label is missing.

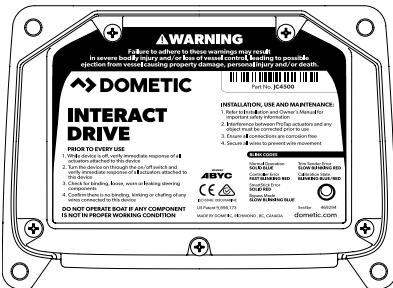


Figure 1.1.

Ensure the dash decal is placed in a visible location on the dash after the Interact Drive installation



Figure 1.2. Dash Decal

⚠ WARNING

The boat operator must be made aware that trim and Jackplate operation is different. It is critical that they get acquainted to Interact Drive operation using this user manual or quick reference card. Failure to do so may result in injury and/or loss of vessel control, leading to possible ejection from vessel causing property damage, personal injury and/or death.

Refer to the quick user guide for reference on how to use the Interact Drive system effectively.

QUICK USER GUIDE

How to adjust engine trim and Jackplate:

- Before moving from stationary position, lower the Jackplate and trim full down.
- After applying throttle, once on plane, trim the engine up. This will lift the bow of the boat and aerate the hull. Continue adjusting trim for optimal ride performance, engine RPM and boat speed.
- Lift the Jackplate up to reduce engine drag, adjusting as needed for optimal ride performance, engine RPM and boat speed.

⚠ WARNING!
Read BOAT OPERATOR'S and Interact Drive Owner's Manuals before use.

Consult the boat user guide for location of the controller ON/OFF switch.

To memorize current Jackplate or Trim position.

To recall memorized Jackplate or Trim position.

For quick controlled motion in set increments.

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PDF# 469275

⚠ WARNING!
Adjusting engine trim or Jackplate height can affect steering control and boat stability. Ensure boat is stable and safe to steer after making engine trim or Jackplate adjustments.

Figure 1.3. Quick User Guide

2 General Information

2.1 Introduction

Before proceeding with the installation, read these instructions thoroughly. Dometic cannot accept responsibility for installations where instructions have not been followed, where substitute parts have been used, or modifications have been made to our products. Warranty may be void if products other than Dometic products are used with this system.

Before Installation

1. Read and understand the Installation and Owner's Manual provided with your controller.
2. Ensure that all components required to complete the installation are on hand (including wires, terminals and the proper tools required for the installation).
3. Dometic components are highly engineered and safety tested to ensure system integrity, DO NOT substitute any component with non-Dometic components as this may compromise system performance/reliability.

Installation

1. Install the controller and the components that connect to the controller as directed in appropriate Installation Manuals.
2. DO NOT modify or substitute any component in any way without written consent from Dometic.
3. Comply with all system ratings/regulations (boat/engine, U.S.C.G.).

WARNING

4. Confirm that there is no interference between the steering cylinder(s), tiebars and the transom, splashwell, outboard engine or Jackplate or any combination of these parts by performing the following steps;
 - 4.1 With engine fully tilted DOWN, turn steering wheel from hard over to hard over and confirm that no interference occurs.
 - if using a hydraulic jack plate the above must also be performed at all the positions of the Jackplate.

- 4.2 Repeat step 'a' with engines tilted UP.
- 4.3 Perform step 4.1 with each engine in DOWN/UP positions confirming that independent TRIM/TILT can be done without any interference.
5. Confirm that the steering cylinder can be fully stroked in both directions as well as full tilt and trim without stretching, chafing, rubbing and/or kinking of the hydraulic hoses.
6. Confirm that extruded nylon tubing has NOT been substituted for Dometic Steering Hose.

Prior to Every Use

1. While device is off, verify immediate response of all actuators attached to this device.
2. Turn the device on through the on/off switch and verify immediate response of all actuators attached to this device.
3. Check for binding, loose, worn or leaking steering or Jackplate components.
4. Confirm there is no binding, kinking or chafing of any wires connected to this device.

WARNING

Do not operate boat if any component is not in proper working condition.

3 System Overview

3.1 How The System Works

Overview

Interact Drive is a NMEA 2000 CAN enabled device designed to give you an additional level of control over Jackplate and Trim position. It offers you an ability to quickly get your boat to speed without a need to look at the gauges. When controller is turned off your Jackplate and Trim switches will operate Jackplates and engine trim in open-loop control, denoted as "Bypass" mode. When the controller switch is on it will engage "Smart" operating mode. For Trim control or Tilt protection please refer to table 4-2 for the additional harness needed to connect the controller to engine trim sender or the NMEA 2000 CAN network. For more resolution of trim control and tilt protection, Dometic recommends

Interact Drive interface directly with an trim sender.

The controller can be wired to:

- Control one Jackplate
 - Optional: connect trim information to Interact Drive for the tilt protection feature
- Control one Jackplate and one engine trim
 - This configuration requires engine trim information
- Control two Jackplates (No engine trim control)
 - Jackplate position is synced
 - Optional: connect trim information to Interact Drive for the tilt protection feature

Please refer to figures 3-1, 3-2 and 3-3 connection details.

Controller Operation

Interact Drive is designed to get you up to speed quickly while helping you maximize your boat performance predictably. You can memorize your favorite Jackplate and trim settings for quick recall later.

The system is designed to help you quickly move jackplate or engine trim to pre-programmed positions or move both in small controlled increments.

For further information refer to section 6

Tilt Protection

If trim information is connected, the Jackplate will move up to a “safe” position when engine in tilt range. This will ensure that when engine is fully tilted there is no contact between the boat transom and engine or steering.

3.2 System Diagrams

Single Jackplate (Gauge Optional)

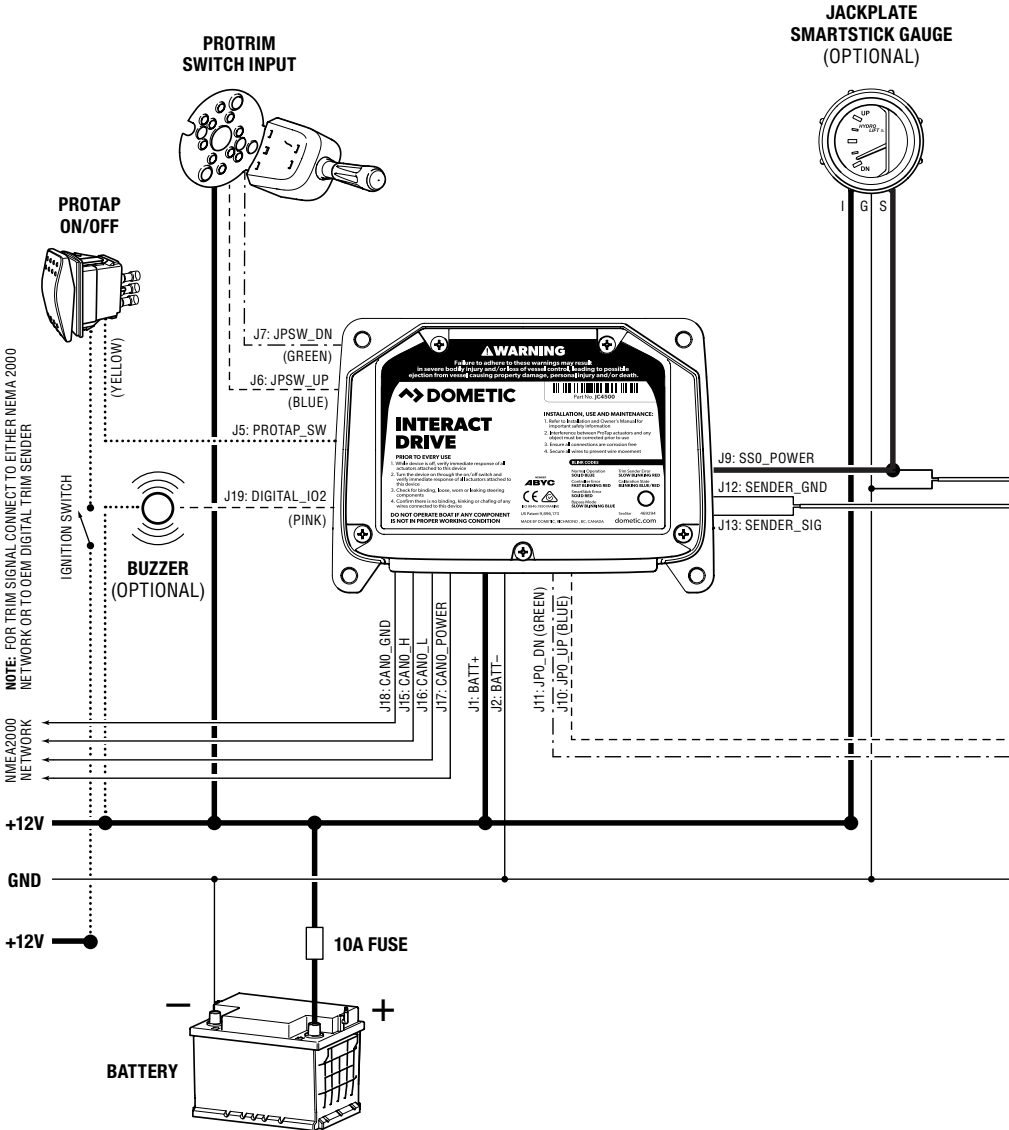
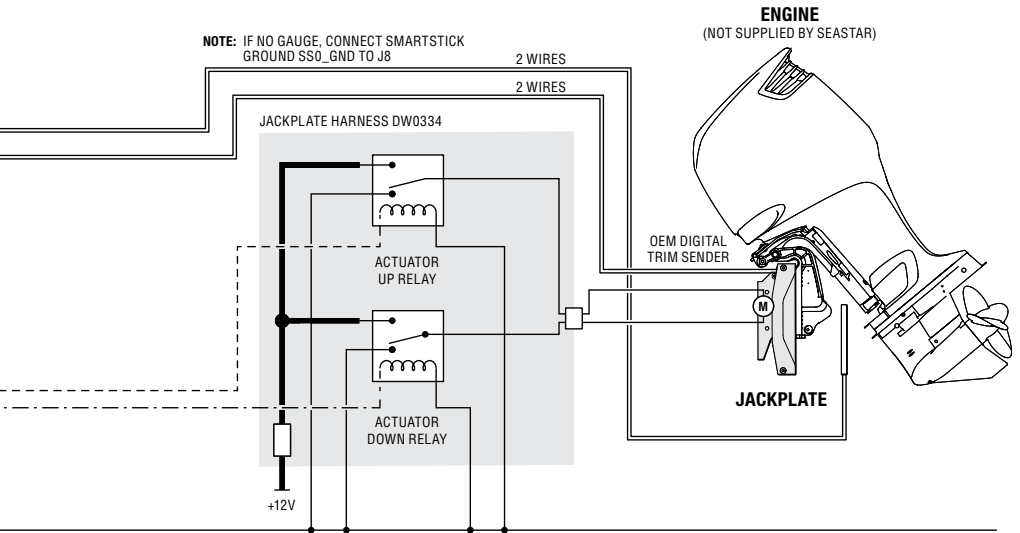


Figure 3.1. Single Jackplate and Gauge.



Referring to figure 4-1 on page 10 match the wiring in the schematic to the pin on the controller.

Single Jackplate and Trim (Gauge Optional)

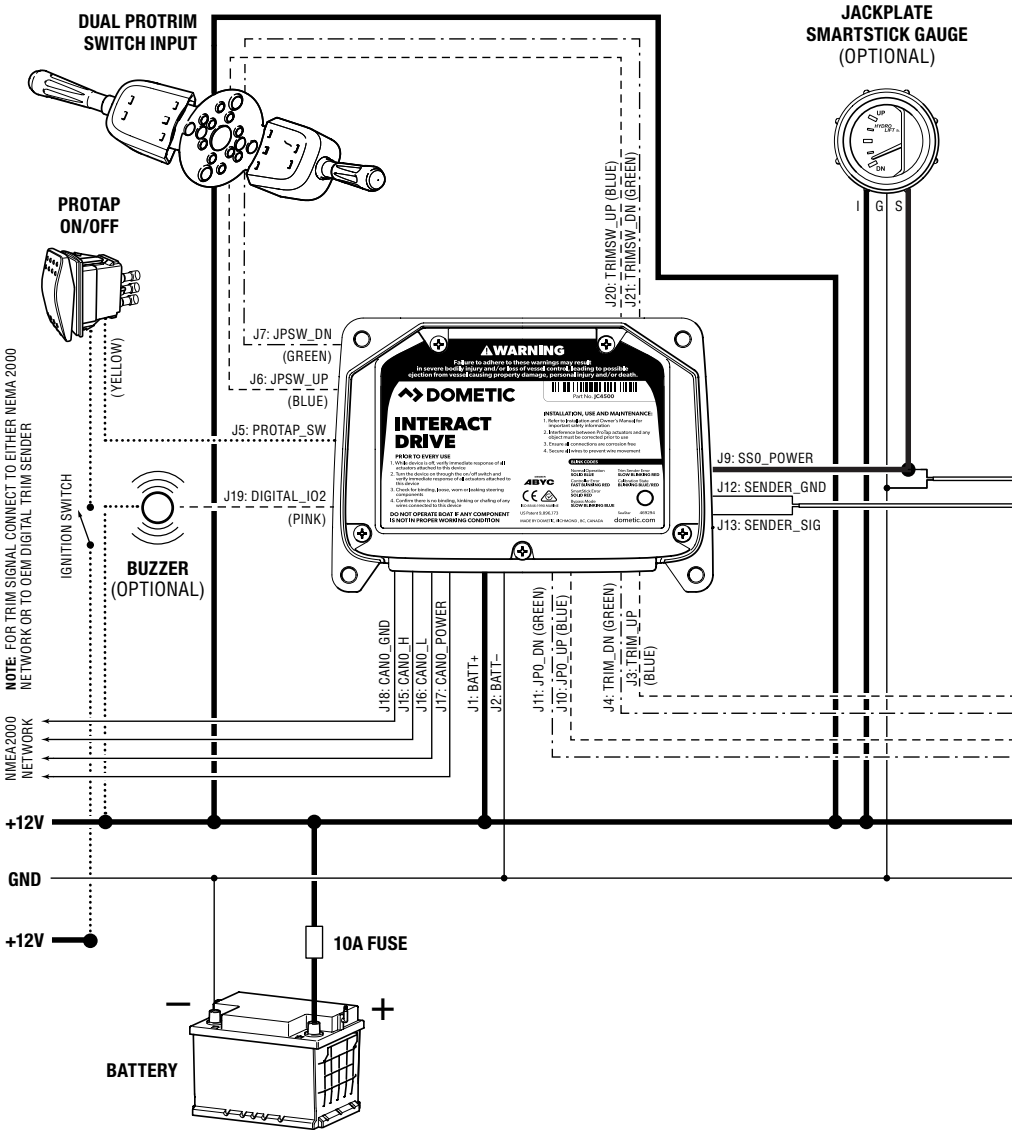
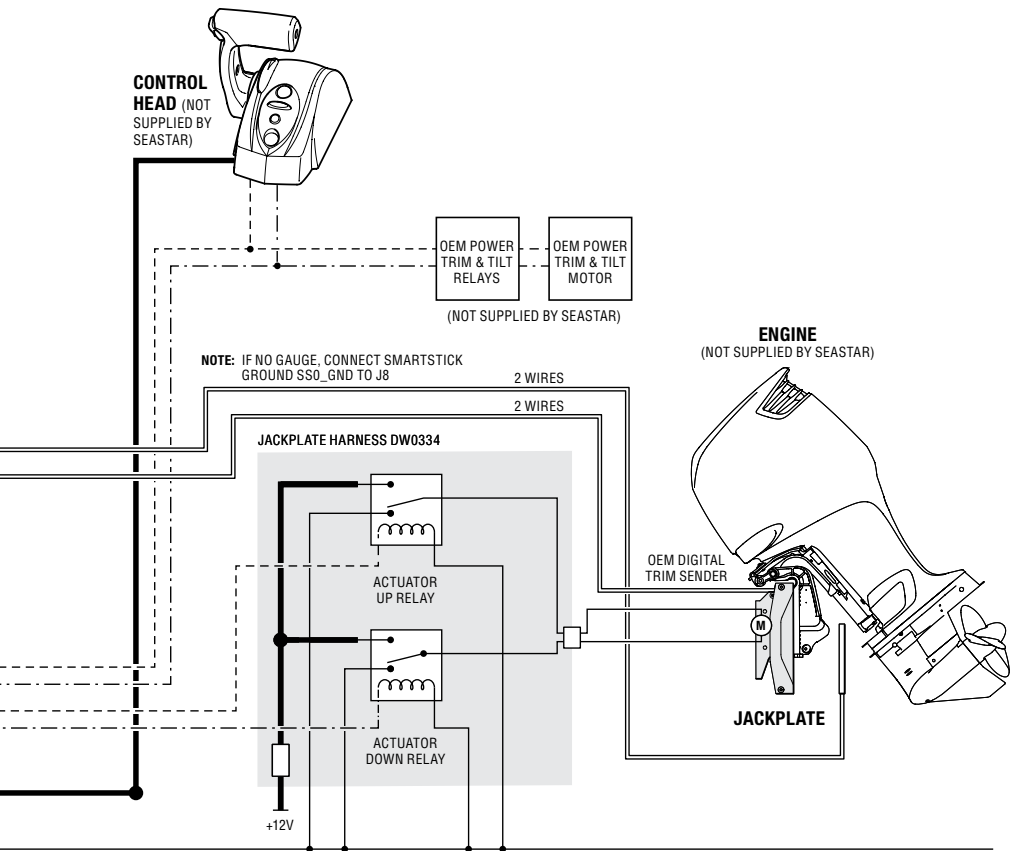


Figure 3.2. Single Jackplate Trim and Gauge.



Referring to figure 4-1 on page 10 match the wiring in the schematic to the pin on the controller.

Twin Jackplate (Gauge Optional)

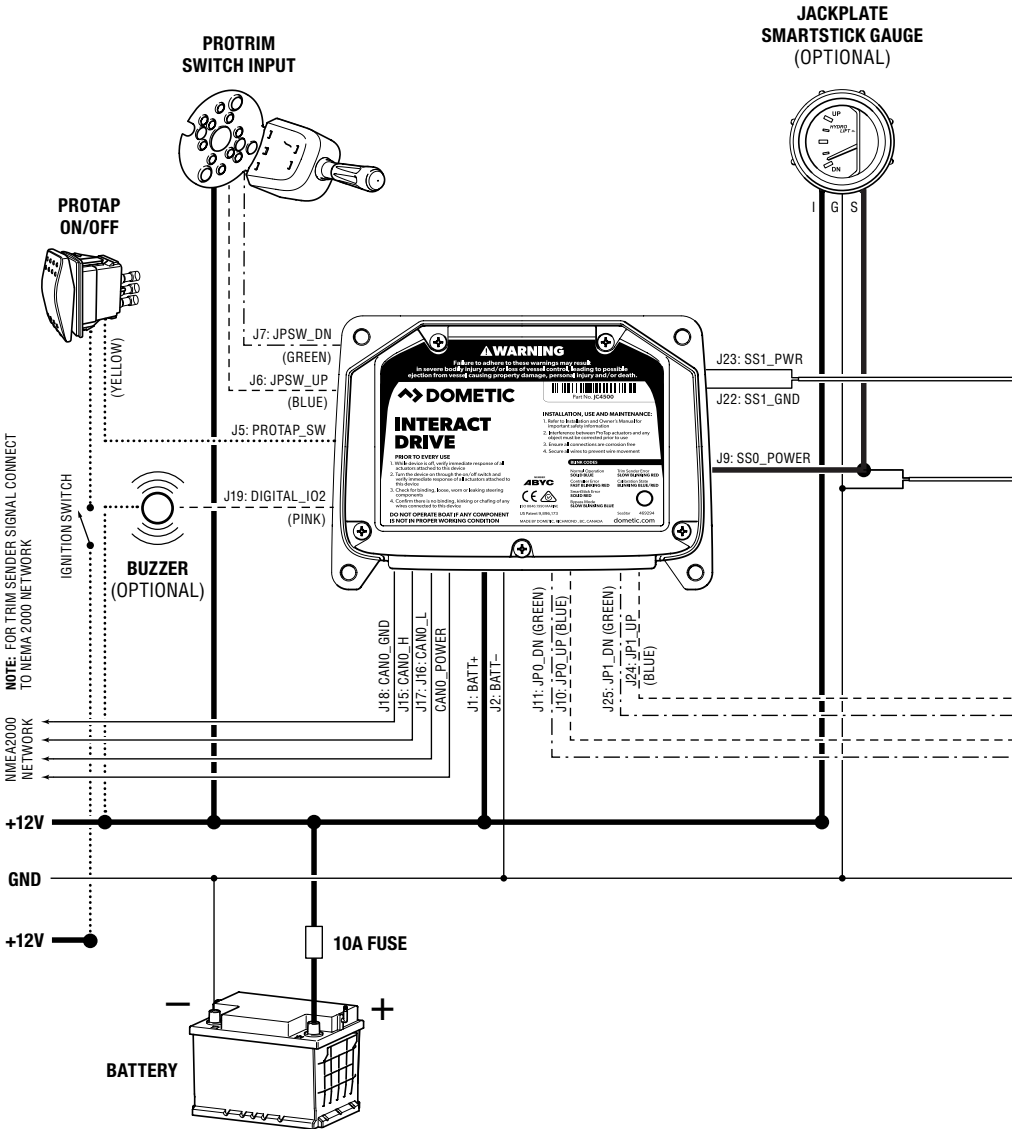
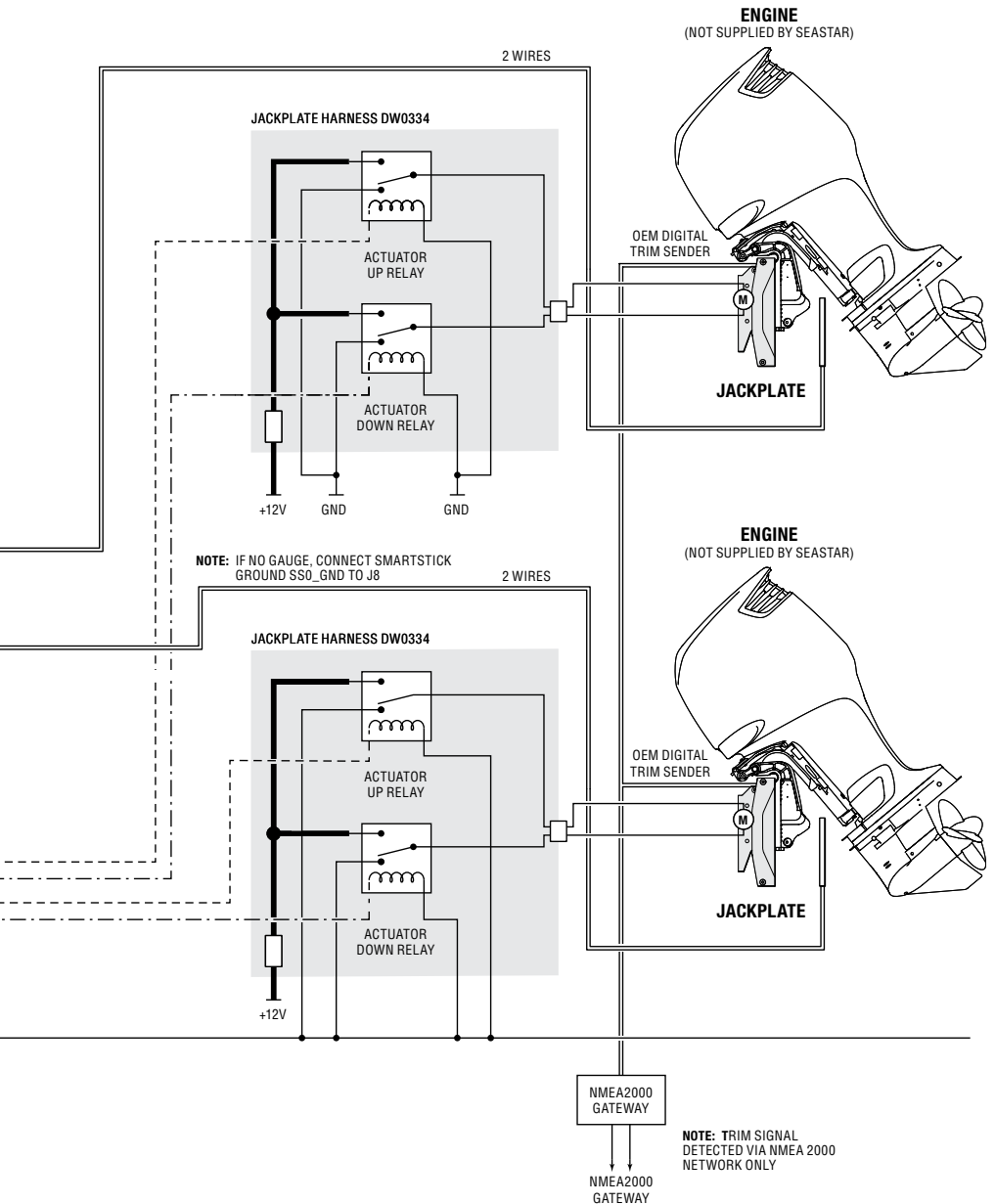


Figure 3.3. Twin Jackplate Gauge.



Referring to figure 4-1 on page 10 match the wiring in the schematic to the pin on the controller.

4 Installation

4.1 Wiring

Use ring terminals or locking type fork terminals that are designed to safely accommodate 18 gauge wire and fit a #6 stud. Power cables attaching to J1 and J2 should use 16 gauge wire.

Recommended tightening torque:

- Terminals: 9 in-lb (1.02 Nm).

⚠ WARNING

Ensure all wires exiting the controller are strain relieved.

⚠ WARNING

Ensure all wires are exiting the controller in a downwards direction.

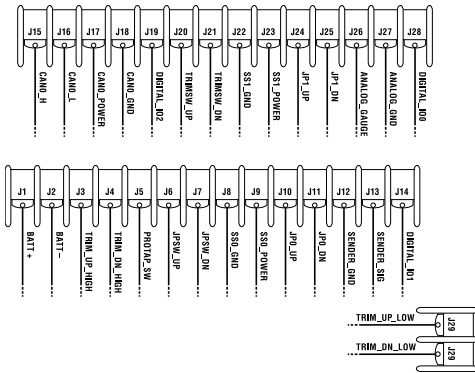


Figure 4.1. Controller Pin Out.

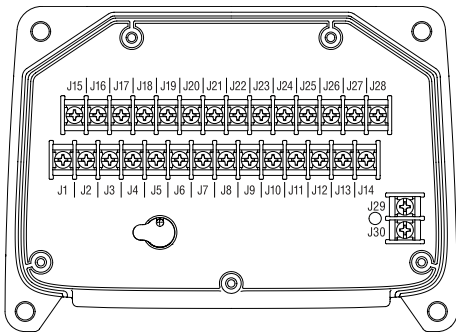


Figure 4.2. Top view of the controller with pin out.

PIN	SIGNAL NAME	DESCRIPTION
J1	BATT+	Power supply input (+) from 12V battery (red).
J2	BATT-	Power supply input (-) from 12V battery (black or yellow).
J3	TRIM_UP_HIGH	Trim Up Output for High Side Control. Connected to engine power trim and tilt up direction (blue).
J4	TRIM_DN_HIGH	Trim Down Output for High Side Control. Connected to engine power trim and tilt down direction (green).
J5	INTERACT_DRIVE_SW	Interact Drive On/Off switch that acts as a wakeup line between Bypass and Smart modes.
J6	JPSW_UP	ProTrim Jackplate Up switch input (blue).
J7	JPSW_DN	ProTrim Jackplate Down switch input (green).
J8	SS0_GND	SmartStick 0 ground line. If Jackplate Gauge is connected, this will not need to be connected (black).
J9	SS0_POWER	With Gauge Connected: Connect to the stud on the gauge labeled as "S". Without a Gauge Connected: Connect to the red wire of the SmartStick on the port Jackplate.
J10	JP0_UP	Connected to the port Jackplate up direction wire (blue).
J11	JP0_DN	Connected to the port Jackplate down direction (green).
J12	SENDER_GND	Digital trim sender input (-) from OEM device.
J13	SENDER_SIG	Digital trim sender input (+) from OEM device.
J14	DIGITAL_IO1	Pending future software release.
J15	CAN0_H	Isolated CAN High communication line from NMEA2K network (white).
J16	CAN0_L	Isolated CAN Low communication line from NMEA2K network (blue).
J17	CAN0_POWER	Isolated CAN power supply input (+) line from NMEA2K network (red).
J18	CAN0_GND	Isolated CAN power supply input (-) line from NMEA2K network (black).
J19	DIGITAL_IO2	Connection for optional external 12V buzzer. Connect the pink lead of the buzzer to this pin.
J20	TRIMSW_UP	ProTrim, Trim Up switch input (blue).
J21	TRIMSW_DN	ProTrim, Trim Down switch input (green).
J22	SS1_GND	SmartStick 1 ground line (black).
J23	SS1_POWER	SmartStick 1 position sense line (red).
J24	JP1_UP	Connected to the starboard Jackplate up direction wire (blue).
J25	JP1_DN	Connected to the starboard Jackplate down direction (green).
J26	ANALOG_GAUGE	Third party analog gauge output (+). 0-5V output based on SmartStick 0 position.
J27	ANALOG_GND	Third party analog gauge output (-).
J28	DIGITAL_IO0	Digital input to enter calibration mode and recalibrate system. Connect 12V to this line at power on to enter calibration mode.
J29	TRIM_UP_LOW	Trim Up Output for Low Side Control. Connected to engine power trim and tilt up direction (blue).
J30	TRIM_DN_LOW	Trim Down Output for Low Side Control. Connected to engine power trim and tilt down direction (green).

Table 4.1.

Direct Trim Signal Wiring Harnesses

Twin engines can not use a direct connection and MUST use NMEA 2000 harness PTK5010.

KIT NO.	DESCRIPTION	APPLICATION
PTK5010	Harness, Interact Drive, CAN, NMEA 2000	All engines with NMEA network gateway
PTK5020	Harness, Interact Drive, for Yamaha 2 wire senders	Yamaha V6 and smaller
PTK5021	Harness, Interact Drive, for Yamaha 3 wire senders	Yamaha V8
PTK5040*	Harness, Interact Drive, for Mercury Optimax/ProXs with SmartCraft	Mercury ProXs, Optimax with SmartCraft network
PTK5041	Harness, Interact Drive, for Mercury Verado sender	Mercury Verado L6
PTK5045	Harness, Interact Drive, for Mercury Verado sender	Mercury Verado V6, V8

* This part number is for a digital trim sender that is specific to the Mercury SmartCraft network.

Table 4.2. Trim signal wiring harnesses.

Pro Trim Switch Input

Please refer to PT1000/PT2000 PT1000-1/PT2000-1 single/dual bezel installation instruction supplied with Pro Trim switch for installation details.

Jackplate SmartStick Gauge (not supplied)

Please refer to System Diagrams in Section 3.2 for gauge installation.

Interact Drive can operate with a SeaStar by Dometic Jackplate Gauge Kit DW4320. This is sold separately from the Interact Drive.

Only one gauge can be installed per Jackplate. It is not possible to operate two gauges for one Jackplate in parallel.

External Buzzer (not supplied)

Please refer to System Diagrams in Section 3.2 for optional buzzer installation.

The Interact Drive has an internal buzzer that, along with the diagnostic LED, notify the operator as to the system status. In addition to the internal buzzer, an external 12V buzzer may be installed should the operator require a more audible feedback from the Interact Drive system.

⚠ WARNING

An external buzzer is required if the Interact Drive is mounted in an area where the internal buzzer cannot be heard or is difficult to hear while the boat is underway.

Direct Trim Sender Connection

If you are connecting an analog trim sender harness it is important to locate a proper trim sender connector. Trace the wire from the trim sender in the midsection all the way to the connector. Once the trim sender T-harness is connected run the wire to the controller through the engine rigging tube.

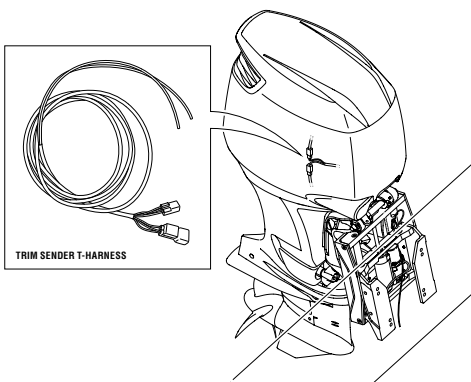


Figure 4.3. Trim Sender connection.

On/Off Switch

Interact Drive on/off switch MUST be connected to the ignition switch OUTPUT line only.

NOTICE: When ignition switch is off, trim signal is lost. Interact Drive will beep loss of trim signal fault if not wired to the ignition switch OUTPUT.

⚠ WARNING

Do not use ignition switch to turn the Interact Drive off during calibration. This will disconnect trim signal and trim positions will not be saved.

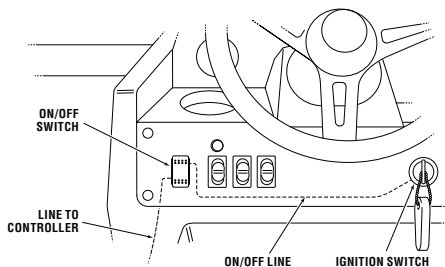


Figure 4.4.

Trim Switch Splicing

To enable trim control the controller needs to be connected to the trim switch wires on the control head.

The Interact Drive has the ability to control trim switches from the control head that are “highside” or “lowside” active. The difference between these two modes is what voltage is required to drive the engine trim (12V or 0V). This is specific to the control head that Interact Drive is interfacing with once installed. Only one pair of the trim outputs (highside or lowside pins) will be used when trim control is enabled. All major engine manufacturers control head’s (Yamaha, Mercury, Suzuki) utilize highside switching, however this can be confirmed by reviewing your engine’s service manual.

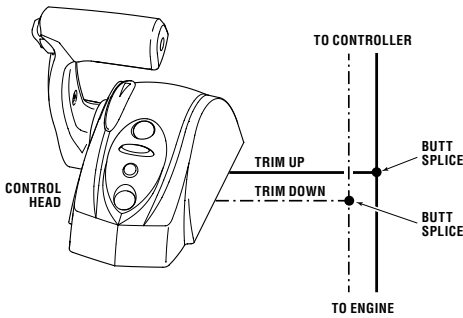


Figure 4.5. Dash Mount Control Head option.

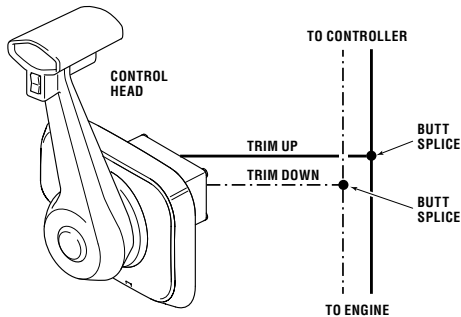


Figure 4.6. Side Mount Control Head option.

Trim Up

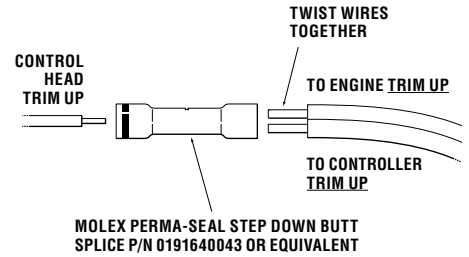


Figure 4.7.

Trim Down

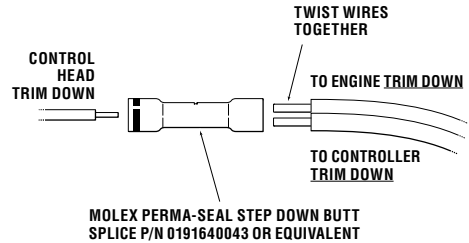


Figure 4.8.

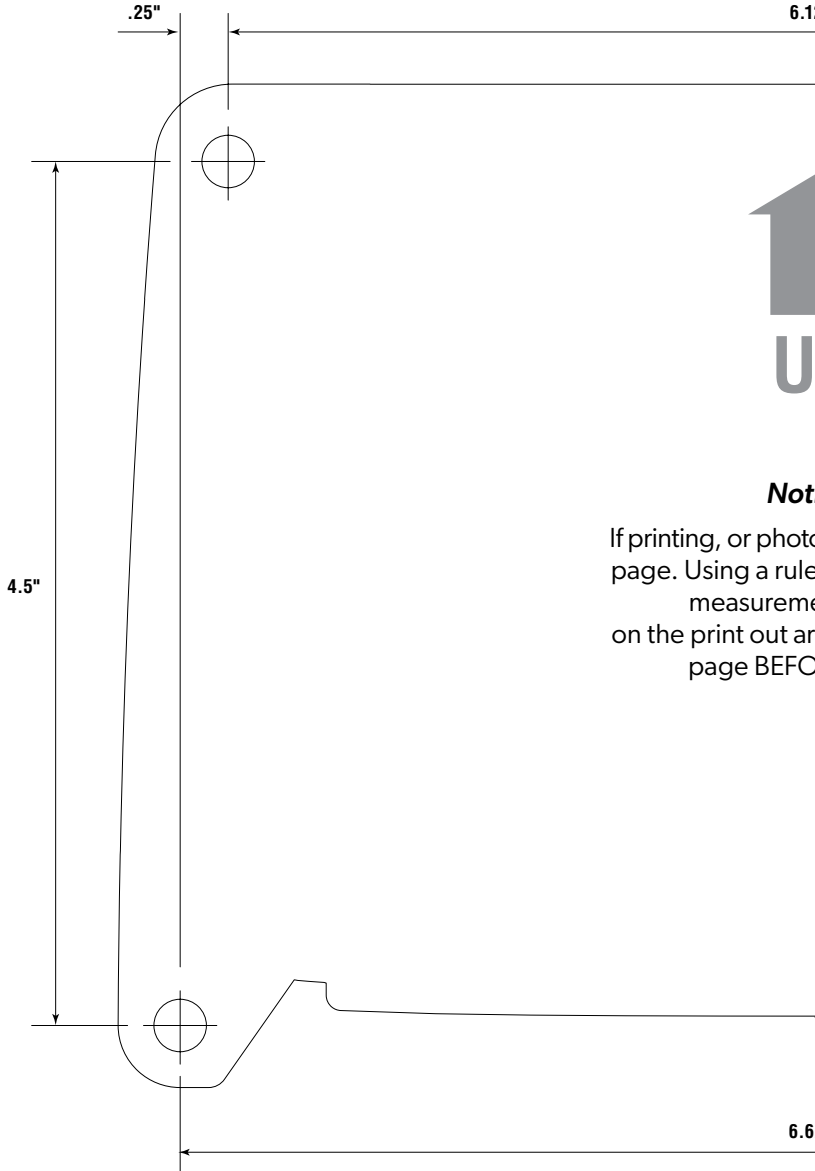
Third-Party Multi-Function Display Integration

When connected to the NEMA 2000 network Interact Drive will broadcast Jackplate height on proprietary PGNs. These PGNs can be read by all Garmin MFDs.

If your Interact Drive was supplied to you with Dometic Digital Switching system with Dometic DCM Module please refer to the Dometic DMC Manual for additional info.

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Interact Drive Wall



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6.6

Mounting Template

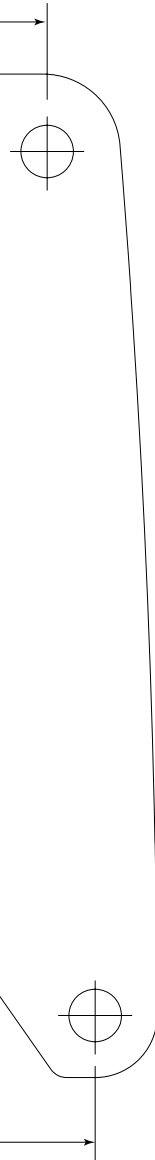
25"



Notice

When copying from this
template, confirm that the
dimensions shown
are as stated on this
template BEFORE drilling.

25"



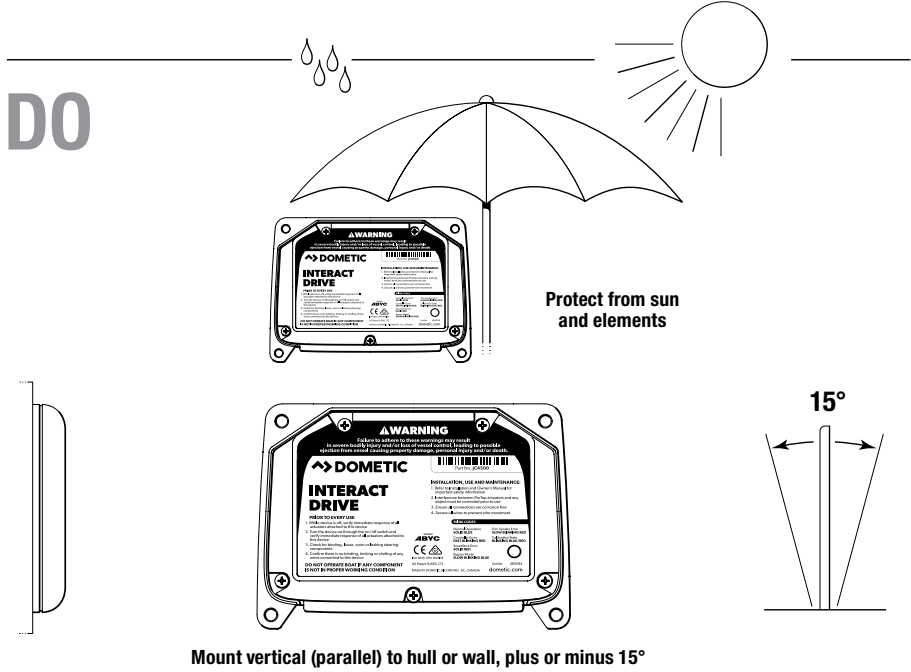
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4.2 Installation Overview

Interact Drive should be mounted in a cool dry area. Ensure that all wire leads are secured after connecting them to the controller. Use four 1/4 inch corrosion proof screws for mounting.

⚠ WARNING

All electrical connections and harness must comply with ABYC wiring standards, be rated for 105°C (221°F), and compliant with SAE-J1128.



DO NOT

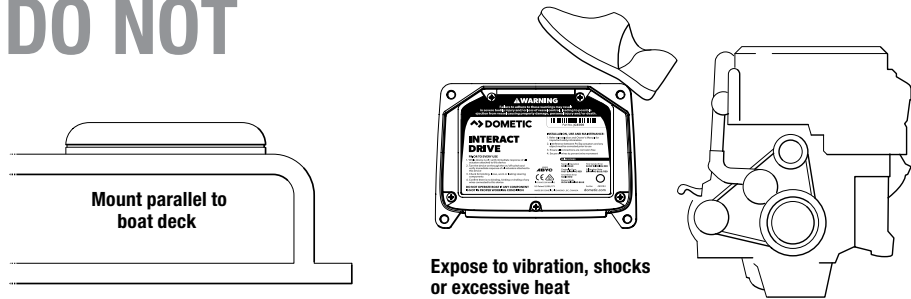


Figure 4.9.

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Top Cover

Once all connections have been properly installed, secure the top cover to the Interact Drive.

Recommended tightening torque:

- Top Cover: 13 in-lb (1.5 Nm).

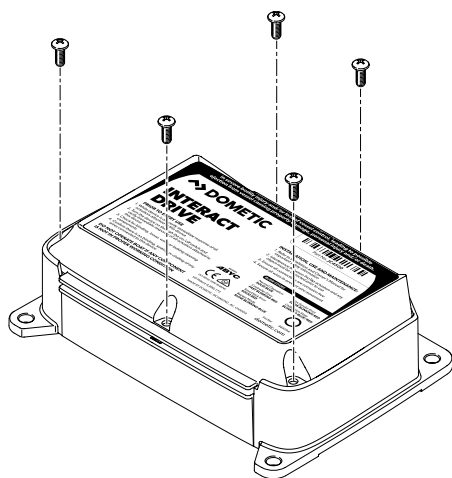


Figure 4.10.

⚠ WARNING

The top cover must be properly secured to the Interact Drive while the boat is underway. Failure to do so may result in injury and/or loss of vessel control, leading to possible ejection from vessel causing property damage, personal injury and/or death.

5 Calibration Procedure

NOTICE: Refer to section 7 for blink and buzzer codes during calibration.

Once the controller is properly installed and turned on for the first time, it will need to be calibrated. This will allow the controller to determine the range of Jackplate and, if connected, trim information from the engine(s). In addition, it will allow you to set a Safe position for tilt protection and a trim to tilt range threshold.

Please follow the procedure below to perform the controller calibration.

If you need to recalibrate the controller apply 12V to J28 pin before turning the controller on. This will place the controller in a calibration mode.

WARNING

If the Jackplate smartstick or trim sender is replaced at any time the system **MUST** be re-calibrated. Failure to do so may result in injury and/or loss of vessel control, leading to possible ejection from vessel causing property damage, personal injury and/or death.

WARNING

Ensure engine is not running during calibration procedure.

WARNING

During the calibration procedure please ensure that the engine can move through the entire trim/tilt range without interference. Please note that the trim down position calibration is performed with a Jackplate in the fully up position.

NOTICE: If trim signal connected, ensure engine key is in ON position for trim sender to be powered.

1. Turn the controller on. When in calibration mode the LED will flash alternating RED/BLUE.
2. Move the Jackplate(s) to the full down position while ensuring engine(s) are in a position that will not cause any interference. Once a hard-stop is reached, continue to drive through the hard-stop for three seconds. An LED and buzzer code will indicate that the Jackplate(s) down hard-stop has been memorized.

3. Move the Jackplate(s) to the full-up position. Once a hard-stop is reached, continue to drive through the hard-stop for three seconds. An LED and buzzer code will indicate that the Jackplate(s) up hard-stop has been memorized.
4. If there is no trim information connected to Interact Drive, turn the controller off using the controller ON/OFF switch and exit calibration mode. If trim signal is present, proceed to step #5.
5. Move the engine(s) trim to the full-down position. Once a hard-stop is reached, double-tap the Jackplate switch down. An LED and buzzer code will indicate that the engine(s) trim down position is memorized.
6. Move the engine(s) trim/tilt to the full-up position. Once a hard-stop is reached, double-tap the Jackplate switch up. An LED and buzzer code will indicate that the engine(s) tilt up position is memorized.
7. With the engine(s) tilt in the full-up position, move the Jackplate(s) to the lowest position where no component interference is possible. This will be memorized as the Jackplate Safe position when turning controller off.
8. Trim the engine(s) down to the highest angle while still within the trim range. This will be memorized as the trim/tilt threshold when turning controller off.
9. Turn controller off using ON/OFF switch. Do not use engine key off as the trim signal will be lost and trim positions will not be memorized.
10. Turn the controller back on. When successfully calibrated the LED will be solid BLUE. Check that the "Smart" mode is operational as per Section 6.0.

WARNING

If trim signal connected, during initial Tilt Protection check, tilt the engine up slowly and ensure that Tilt Protection is engaged. Failure to do so may result in damage to the vessel or engine components..

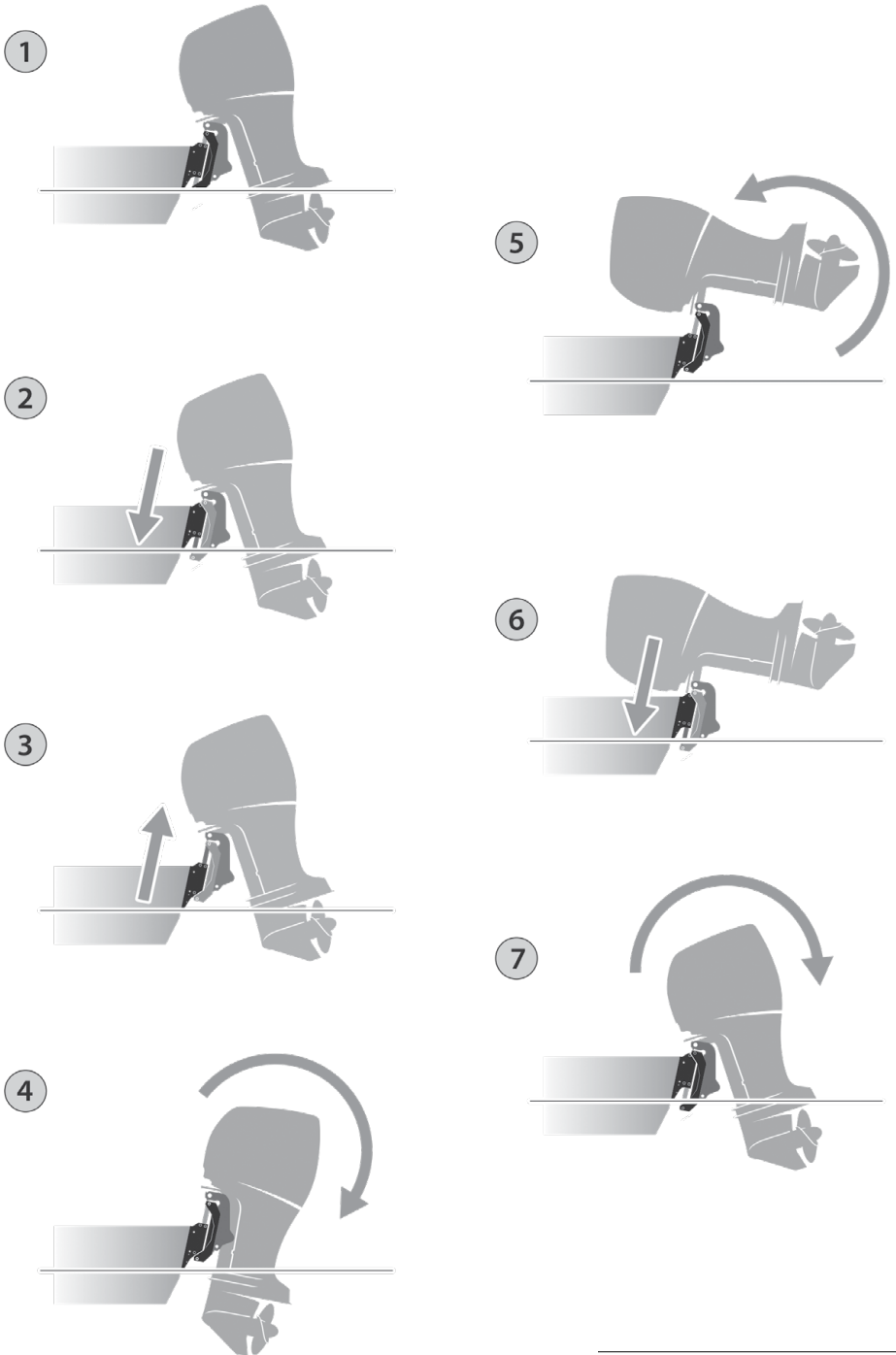


Figure 5.1.

6 Interact Drive Operation

Please see below for a detailed description of each mode and how to utilize the controller.

6.1 Jackplate Control

- Memorize two of your favorite Jackplate positions by holding a Jackplate toggle switch up or down for more than 5 seconds.
- Recall the two memorized position by holding the Jackplate toggle switch up or down for 1-5 seconds.
- Tap the Jackplate toggle switch up or down to move the plate in controlled 1/4" increments.
- Multiple taps on the Jackplate toggle switch are memorized and plate will move the same number of increments without pausing.
- Interact Drive can control up to 2 Jackplates while making sure they are in sync with each other.

WARNING

Tilt protection not engaged when Interact Drive turned off.

Tilt protection not engaged if there is a loss of trim signal.

When tilting the engine, always visually check that Jackplate is up to prevent any steering or engine damage.

Trim Control

To enable, connect trim sender either direct or using a NMEA 2000 harness as per Table 4-2:

- Memorize two of your favorite trim positions by holding the trim toggle switch up or down for more than 5 seconds.
- Recall the two memorized trim position by holding the trim toggle switch up or down for 1-5 seconds.
- Tap the trim toggle switch up or down to move the trim in set increments of 1/20 of trim range.

NOTICE: Trim control only available for single engine applications.

NOTICE: Trim control available in trim range only. If engine in tilt range the switch will revert to normal operation. Move engine back to trim range for Trim Control.

Tilt Protection

Connecting a trim sender signal direct via a harness or over NMEA 2000 network to the controller will allow you to set engine tilt protection during the initial calibration. It allows you to set the safe position and trim/tilt threshold. When engine moves to tilt range the Jackplate will move up to a Safe position.

NOTICE: Dual engine tilt protection only available through a NMEA 2000 harness connection.

7 Troubleshooting

LED Codes

INTERACT DRIVE STATUS	COLOUR	BLINK PERIOD	DESCRIPTION
Interact Drive Error	Red	500ms On 500ms Off	A non-SmartStick or trim sender fault is present that is preventing the Interact Drive from performing at 100%.
SmartStick Error	Red	Solid Colour	Fault 0x7FDA[x] is active.
Trim Sender Error	Red	1000ms On 1000ms Off	Fault 0x7FDB[x] is active.
Calibration Hardstop Achieved	Purple	1000ms On 1000ms Off	Jackplate or Trim Hardstop achieved during calibration mode. This blink sequence will be synchronized with the buzzer for a calibration hardstop.
Calibration State Active	Red/Blue	1000ms Red 1000ms Blue	Interact Drive is in a calibration state.
Interact Drive Bypass Mode	Blue	1000ms On 1000ms Off	Interact Drive is in a Bypass mode without a fault present

Table 7.1. LED Codes

NOTICE: If error is reported the controller will switch to Bypass Mode. Only one error is reported. To clear the error turn the controller off then on. If the error is not cleared please contact Dometic Technical Support.

Buzzer Codes

SCENARIO	NO. OF PULSES	PERIOD OF PULSE	DESCRIPTION
Danger Fault Active	Indefinite	1000ms On 1000ms Off	Provide feedback to the user of an active danger fault.
Memory Save Command Invoked	1 pulse	500ms On 500ms Off	Provide feedback to the user that a memory save command has been invoked (Jackplate or Trim).
Jackplate Calibration Hardstop Achieved	1 pulse	1000ms On 1000ms Off	Provide feedback to the user that a Jackplate hardstop has been achieved. This buzzer sequence will be synchronized with the LED for a calibration hardstop.
Trim Calibration Hardstop Achieved	2 pulses	1000ms On 1000ms Off	Provide feedback to the user that a Jackplate hardstop has been achieved. This buzzer sequence will be synchronized with the LED for a calibration hardstop.
Trim Signal Lost	3 pulses	1000ms On 1000ms Off	Interact Drive has lost trim position information

8 Warranty

8.1 Statement of Limited Warranty

We warrant to the original retail purchaser that Marine Canada Acquisition Inc. DBA Dometic (herein forward referred to as Dometic) products have been manufactured free from defects in materials and workmanship. This warranty is effective for two years from date of purchase, excepting that where Dometic products are used commercially or in any rental or income producing activity, then this warranty is limited to one year from the date of purchase.

We will provide replacement product without charge, for any Dometic product meeting this warranty, which is returned (freight prepaid) within the warranty period to the dealer from whom such product were purchased, or to us at the appropriate address. In such a case Dometic products found to be defective and covered by this warranty, will be replaced at Dometic' option, and returned to the customer.

The above quoted statement is an extract from the complete Dometic products warranty statement. A complete warranty policy is available in our Dometic products catalogue.

8.2 Return Good Procedure

Prior to returning product to Dometic under warranty, please obtain a Return Goods Authorization number (claim number).

Be sure to label the goods with:

- a) the name and address of the sender, and
- b) the return goods authorization number (claim number)

Please address the returned goods as follows:

From U.S.A.	From Canada
RGA # ?	RGA # ?
Dometic	Dometic
c/o UPS-SCS	3831 No.6 Road
19308 70th Ave S.	Richmond, B.C.
Kent, WA 98032	Canada V6V 1P6

8.3 Technical Support

Phone: 604-248-3858

Email: seastar@dometic.com

Hours: Monday to Friday 05:00 – 15:30 PST

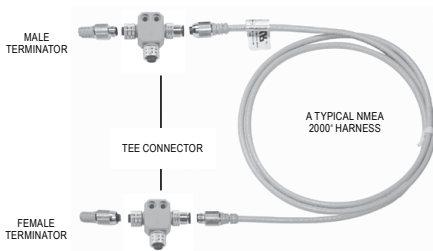
Web: www.dometic.com

9 Appendix

9.1 CAN Basic Network

The NMEA 2000® protocol allows several types of harness. The one shown in this document is the smaller type used in pleasure boats and small vessels. The larger harness is used in shipboard applications. Any manufacturer may use their own harness but to adhere to the standard they must have an adapter harness that allows easy connection to the approved harness. All Dometic CAN Bus harness meet the NMEA 2000® standard and will work with any other suppliers' harness that meet the NMEA 2000® standard.

While the NMEA 2000® standard allows separate wires and terminals all CAN Bus harness use the connectors shown in this manual. They are easy to install and result in a high quality, rugged, waterproof installation. The harness should never be cut and spliced.



CM100XX: A typical NMEA 2000® harness

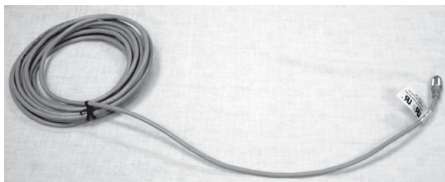


Figure 9.1.

CAN Bus Connectors



CM10051: Male Terminator Terminator



CM10052: Female Terminator

Figure 9.2.

Tee Connectors:

Supplied by several vendors. Appearance may vary – parts are interchangeable.

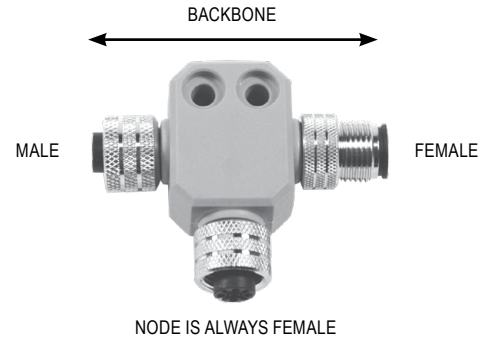


Figure 9.3.

Note regarding connectivity of tee connectors:

- When connecting a tee connector to a component always install via the middle connection (“NODE”).
- When connecting a tee connector to a CAN Bus harness to connect components that are far from each other, always install via the male/ female end of the connector (whichever applies).
- Hand-tighten after the connection is made. DO NOT tightly tie down the tee connectors, as this will create stress.

CAN Bus Connectivity

The Network must consist of a single harness run to which devices are connected by means of a tee connector. All products must connect onto the node part of the tee connector. Each end of the harness must have a terminator. It is essential there be a total of two, and ONLY two, terminators - one located at each end of the backbone.

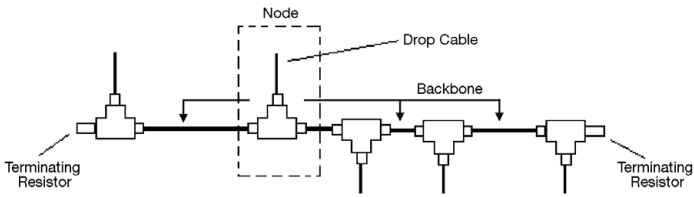


Figure 9.4.

Note: a tee connector with nothing attached to its node is OK and will not effect the network. NEVER use a terminator to cap the node of an unused tee connector.

Electrical Harness

The cabling that is used conforms to the DeviceNet standard and was developed for Industrial applications. In general the harness are molded and the connection area is sealed with o-ring gaskets to provide a good seal from the environment. The harness are available in a variety of lengths.

NOTICE: The electrical harness must not be cut or spliced. Replace worn or frayed harness.

When securing the harness and especially when tying down a number of direct connected tees never pull them down so tight as to cause strain or put a curve in the tees as this may cause a failure.

When installing a NMEA 2000® CAN Bus system there are several things to keep in mind:

- The harness ends are male and female. To avoid a mismatch it is best to work from one end toward the other. If you must work from both ends toward the middle assure that the mating point will be a male/female connection.
- It is wise to plan for expansion. With so many new NMEA 2000® products entering the market and the ability to connect on to the bus for testing it is sometimes wise to use two harness where one would suffice. The connection of the two harness can later be separated so additional tees can be inserted to add another product or test equipment.
- On 24 volt systems, a DC to DC converter or separate 12 volt battery is required.

Powering the Bus

The CAN Bus requires DC power. The voltage range is 9 to 16 volts. The power may be supplied by one or more of the products on the Data Bus or from a separate source. Most equipment manufacturers strongly recommends that at least two independent sources are used to supply the data bus power.

CAN Bus Power

The CAN Bus is used to supply power to all the items that are connected to the bus. For items drawing less than one amp, not having any other power connection, or another path back to ground the entire power for the item may be pulled from the CAN Bus. This requires the CAN Bus to have adequate sources of power.

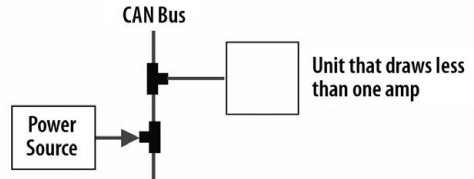


Figure 9.5.

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